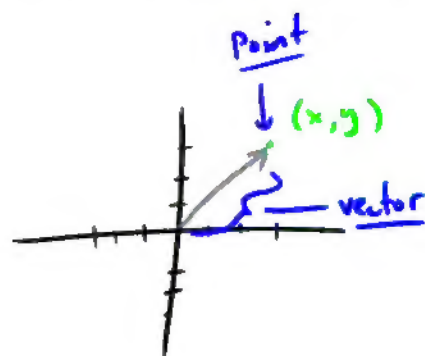


Last Time: <sup>\*</sup> Matrix operations, reps of lin systems w/ mats.

## Geometry

Case study:  $\mathbb{R}^2$



Points: pairs (in  $\mathbb{R}^2$ ) of real numbers.

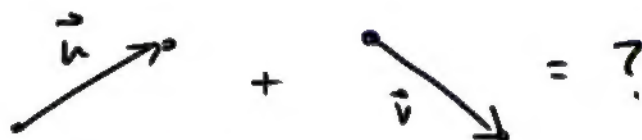
Vector: directed line segment connecting two points.

↳ can be represented as a pair (in  $\mathbb{R}^2$ )

Vector operations: matrix operations on vectors  
(for the most part).

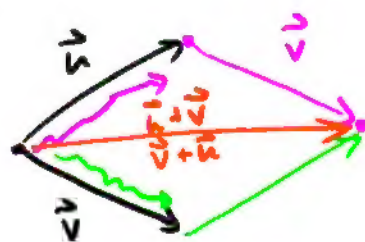
Ex: the sum of vectors  $\vec{u}$  and  $\vec{v}$  is the matrix sum.

Geometrically:



If  $\vec{u} = (x_1, y_1)$ ,  $\vec{v} = (x_2, y_2)$ , then

$$\vec{u} + \vec{v} = (x_1 + x_2, y_1 + y_2)$$



NB: These vectors live in  $\mathbb{R}^2$ , but in general,  
we'll work in  $\mathbb{R}^n = \{\text{vectors with } n \text{ components}\}$ .

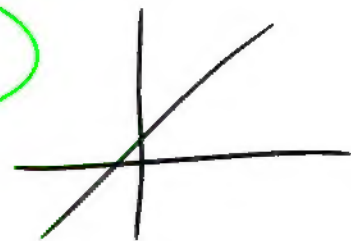
Lines: Algebraically, lines can be represented via:

Parameterization:  $\{\vec{p} + t\vec{v} : t \in \mathbb{R}\}$



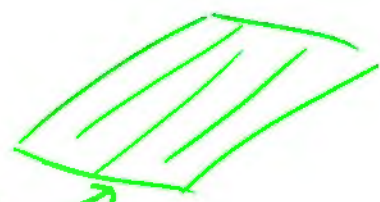
Equation (in  $\mathbb{R}^2$ ):

$$ax + by = c$$



Remark: In higher dimensions, 1 linear equation doesn't describe a line ☹

in  $\mathbb{R}^3$ :  $ax + by + cz = d$   
yields a plane



↳ the plane parameterizes like so: ( $a \neq 0$ )

$$\begin{cases} x = \frac{1}{a}(d - bs - ct) \\ y = s \\ z = t \end{cases}$$

$$\Rightarrow \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} d/a \\ 0 \\ 0 \end{bmatrix} + s \begin{bmatrix} -b/a \\ 1 \\ 0 \end{bmatrix} + t \begin{bmatrix} -c/a \\ 0 \\ 1 \end{bmatrix}$$

$$\therefore \left\{ \begin{bmatrix} x \\ y \\ z \end{bmatrix} \in \mathbb{R}^3 : ax + by + cz = d \right\}$$

$$= \left\{ \begin{bmatrix} d/a \\ 0 \\ 0 \end{bmatrix} + s \begin{bmatrix} -b/a \\ 1 \\ 0 \end{bmatrix} + t \begin{bmatrix} -c/a \\ 0 \\ 1 \end{bmatrix} : s, t \in \mathbb{R} \right\}$$

↑ parameterization of our plane...

NB: 2 free variables  $\Rightarrow$  dimension 2  $\Rightarrow$  2-flat  
i.e. planes are 2-flats.

Defn: A  $\rightarrow$  k-flat (in  $\mathbb{R}^n$ ) is a k-dimensional version of a line. I.e. a set of vectors which can be expressed as:

$$\left\{ \vec{p} + t_1 \vec{v}_1 + t_2 \vec{v}_2 + \dots + t_k \vec{v}_k : t_1, t_2, \dots, t_k \in \mathbb{R}^k \right\}$$

For some collection of (linearly independent) vectors  $v_1, v_2, \dots, v_k$

NB: Specially named flats in  $\mathbb{R}^n$

points: 0-flats

planes: 2-flats

lines: 1-flats

hyperplanes:  $(n-1)$ -flats

Lem: The solution set of a linear system is always a  $k$ -flat for some  $k$ .

Point: Linear systems have some rich associated geometry.

## Geometry and Vector Operations

Defn: The length of a vector  $\vec{v} = (v_1, v_2, \dots, v_n)$  is  $|\vec{v}| := \sqrt{v_1^2 + v_2^2 + \dots + v_n^2}$ .

Lem: For all  $\vec{v} \in \mathbb{R}^n$ ,  $|\vec{v}| \geq 0$ . Furthermore,  $|\vec{v}| = 0$  precisely when  $\vec{v} = \vec{0}$ .

Reason: Sums of nonnegative numbers are nonnegative. Squares of any (real) numbers are nonnegative (so the square root of a sum of squares is well-defined).

Principal square roots are nonnegative.

If  $\sum_{i=1}^n v_i^2 = 0$ , necessarily each  $v_i = 0$ .

Defn: The dot product (i.e. inner product) of vectors  $\vec{u}, \vec{v} \in \mathbb{R}^n$  is defined by

$$\vec{u} \cdot \vec{v} = (u_1, u_2, \dots, u_n) \cdot (v_1, \dots, v_n) = u_1 v_1 + u_2 v_2 + \dots + u_n v_n.$$



Lemma: For all  $\vec{v} \in \mathbb{R}^n$ ,  $|\vec{v}| = \sqrt{\vec{v} \cdot \vec{v}}$ . (i.e.  $\vec{v} \cdot \vec{v} = |\vec{v}|^2$ ).

pf: Let  $\vec{v} = (v_1, v_2, \dots, v_n)$  be arbitrary. On one hand,

$$|\vec{v}| = \sqrt{v_1^2 + v_2^2 + \dots + v_n^2} \quad \text{On the other hand,}$$

$$\begin{aligned} \sqrt{\vec{v} \cdot \vec{v}} &= \sqrt{(v_1, v_2, \dots, v_n) \cdot (v_1, v_2, \dots, v_n)} = \sqrt{v_1 \cdot v_1 + v_2 \cdot v_2 + \dots + v_n \cdot v_n} \\ &= \sqrt{v_1^2 + v_2^2 + \dots + v_n^2}, \text{ so } |\vec{v}| = \sqrt{\vec{v} \cdot \vec{v}} \text{ as desired } \square \end{aligned}$$

Ex: Let  $\vec{u} = (3, 0, -1, 5)$ ,  $\vec{v} = (-2, -3, 6, 1)$

$$\vec{u} \cdot \vec{v} = (3, 0, -1, 5) \cdot (-2, -3, 6, 1)$$

$$= 3 \cdot -2 + 0 \cdot -3 + -1 \cdot 6 + 5 \cdot 1$$

$$= -6 + 0 - 6 + 5 = -7 \quad \square$$

NB: The dot product can be thought of as a function

$$\cdot : \mathbb{R}^n \times \mathbb{R}^n \longrightarrow \mathbb{R}$$

Prop (Properties of Dot Product): Let  $\vec{u}, \vec{v}, \vec{w} \in \mathbb{R}^n$ .

$$\textcircled{1} \quad \vec{u} \cdot \vec{v} = \vec{v} \cdot \vec{u}$$

$$\begin{aligned} \text{pf: } (u_1, u_2, \dots, u_n) \cdot (v_1, v_2, \dots, v_n) &= u_1 v_1 + u_2 v_2 + \dots + u_n v_n \\ &= v_1 u_1 + v_2 u_2 + \dots + v_n u_n \\ &= (v_1, v_2, \dots, v_n) \cdot (u_1, u_2, \dots, u_n). \quad \square \end{aligned}$$

$$\textcircled{2} \quad \vec{u} \cdot (\vec{v} + \vec{w}) = \vec{u} \cdot \vec{v} + \vec{u} \cdot \vec{w} \quad \leftarrow$$

$$\begin{aligned} \text{pf: } (u_1, u_2, \dots, u_n) \cdot ((v_1, v_2, \dots, v_n) + (w_1, w_2, \dots, w_n)) \\ &= (u_1, u_2, \dots, u_n) \cdot (v_1 + w_1, v_2 + w_2, \dots, v_n + w_n) \\ &= u_1(v_1 + w_1) + u_2(v_2 + w_2) + \dots + u_n(v_n + w_n) \\ &= (\underline{u_1 v_1} + \underline{u_1 w_1}) + (\underline{u_2 v_2} + \underline{u_2 w_2}) + \dots + (\underline{u_n v_n} + \underline{u_n w_n}) \\ &= (u_1 v_1 + u_2 v_2 + \dots + u_n v_n) + (u_1 w_1 + u_2 w_2 + \dots + u_n w_n) \\ &= (u_1, u_2, \dots, u_n) \cdot (v_1, v_2, \dots, v_n) + (u_1, u_2, \dots, u_n) \cdot (w_1, w_2, \dots, w_n) \quad \square \end{aligned}$$

$$\textcircled{3} (c\vec{u}) \cdot \vec{v} = c(\vec{u} \cdot \vec{v}) = \vec{u} \cdot (c\vec{v})$$

$$\begin{aligned} \text{pf: } (c(u_1, u_2, \dots, u_n)) \cdot (v_1, v_2, \dots, v_n) &= (cu_1, cu_2, \dots, cu_n) \cdot (v_1, v_2, \dots, v_n) \\ &= (cu_1)v_1 + (cu_2)v_2 + \dots + (cu_n)v_n \\ &= c(u_1v_1) + c(u_2v_2) + \dots + c(u_nv_n) \\ &= c(u_1v_1 + u_2v_2 + \dots + u_nv_n) \\ &= c((u_1, u_2, \dots, u_n) \cdot (v_1, v_2, \dots, v_n)). \end{aligned}$$

$$\text{So } (c\vec{u}) \cdot \vec{v} = c(\vec{u} \cdot \vec{v}). \quad \text{Moreover}$$

$$\vec{u} \cdot (c\vec{v}) = (c\vec{v}) \cdot \vec{u} = c(\vec{v} \cdot \vec{u}) = c(\vec{u} \cdot \vec{v})$$

□

$$\textcircled{4} \vec{0} \cdot \vec{v} = 0$$

$$\begin{aligned} \text{pf: } (0, 0, \dots, 0) \cdot (v_1, v_2, \dots, v_n) &= 0v_1 + 0v_2 + \dots + 0v_n \\ &= 0(v_1 + v_2 + \dots + v_n) \\ &= 0 \end{aligned}$$

□

Next time: Tie Geometry of dot product to the algebraic properties we just proved.